A SEQUENT CALCULUS FOR OPETOPES CT 2019

Pierre-Louis Curien¹ **Cédric Ho Thanh**¹ Samuel Mimram² July 9th, 2019

¹IRIF, Paris University

²LIX, École Polytechnique

This presentation informally presents some of the main notions and results of [Curien et al., 2019] arXiv:1903.05848, namely a "unnamed" syntax for opetopes, and a sequent calculus Opt?. Opetopes

Syntax

Opt?: a sequent calculus for opetopes

Examples

Conclusion

Opetopes

In a nutshell...

Opetopes are shapes (akin to globules, cubes, simplices, dendrices, etc.) designed to represent the notion of composition in every dimension. As such, they were introduced in [Baez and Dolan, 1998] to describe laws and coherence in weak higher categories.

In a nutshell...

Opetopes are shapes (akin to globules, cubes, simplices, dendrices, etc.) designed to represent the notion of composition in every dimension. As such, they were introduced in [Baez and Dolan, 1998] to describe laws and coherence in weak higher categories.

They have been actively studied over the recent years in [Hermida et al., 2002], [Cheng, 2003], [Leinster, 2004], [Kock et al., 2010] and applied to the theory of polygraphs in [Ho Thanh, 2018a].

In a nutshell...

Opetopes are shapes (akin to globules, cubes, simplices, dendrices, etc.) designed to represent the notion of composition in every dimension. As such, they were introduced in [Baez and Dolan, 1998] to describe laws and coherence in weak higher categories.

They have been actively studied over the recent years in [Hermida et al., 2002], [Cheng, 2003], [Leinster, 2004], [Kock et al., 2010] and applied to the theory of polygraphs in [Ho Thanh, 2018a].

A first syntactic account of opetopes has been tried in [Hermida et al., 2002], but does not seem usable for any computation.

They are **pasting diagrams** where every cell is **many-to-one** i.e. many inputs, one output. Here is an example of a 3-opetope:



They are **pasting diagrams** where every cell is **many-to-one** i.e. many inputs, one output. Here is an example of a 3-opetope:



Every cell denoted by a ↓ above has dimension 2, so that a 3-opetope really is a pasting diagram of cells of dimension 2.

They are **pasting diagrams** where every cell is **many-to-one** i.e. many inputs, one output. Here is an example of a 3-opetope:



Every cell denoted by a \downarrow above has dimension 2, so that a 3-opetope really is a pasting diagram of cells of dimension 2.

We further ask those cells of dimension 2 to be 2-opetopes, i.e. pasting diagram of cells of dimension 1 (the simple arrows →).



Definition

An *n*-dimensional opetope (or just *n*-opetope) is a pasting diagram of (n - 1)-opetopes,



Definition

An *n*-dimensional opetope (or just *n*-opetope) is a pasting diagram of (n - 1)-opetopes, i.e. a finite set of (n - 1)-opetopes glued along (n - 2)-opetopes,



Definition

An *n*-dimensional opetope (or just *n*-opetope) is a pasting diagram of (n - 1)-opetopes, i.e. a finite set of (n - 1)-opetopes glued along (n - 2)-opetopes, in a "well-defined manner".

• There is a unique 0-dimensional opetope, which we'll call the **point**:

•

• There is a unique 0-dimensional opetope, which we'll call the **point**:

•

 \rightarrow .

• There is a unique 1-opetope, the arrow:

• There is a unique 0-dimensional opetope, which we'll call the **point**:

.

• There is a unique 1-opetope, the arrow:

• There is a unique 0-dimensional opetope, which we'll call the **point**:

.

• There is a unique 1-opetope, the arrow:

• There is a unique 0-dimensional opetope, which we'll call the **point**:

.

• There is a unique 1-opetope, the arrow:

• There is a unique 0-dimensional opetope, which we'll call the **point**:

.

• There is a unique 1-opetope, the arrow:

$$\mathbf{n} = \underbrace{(n-1)}_{(n)} \underbrace{(n-1)}_{(n$$

• There is a unique 0-dimensional opetope, which we'll call the **point**:

.

• There is a unique 1-opetope, the arrow:









• The induction goes on: 4-opetopes are pasting diagrams of 3-opetopes:



• The induction goes on: 4-opetopes are pasting diagrams of 3-opetopes:



This is getting out of hand...

Motivation

Problem

1. The graphical approach is neither formal nor manageable for dimensions ≥ 4 .

Problem

- 1. The graphical approach is neither formal nor manageable for dimensions ≥ 4 .
- 2. A formal definition either uses *T*-operads [Leinster, 2004] or polynomial monads and trees [Kock et al., 2010], which as is, are not suited for automated computations.

Problem

- 1. The graphical approach is neither formal nor manageable for dimensions ≥ 4 .
- 2. A formal definition either uses *T*-operads [Leinster, 2004] or polynomial monads and trees [Kock et al., 2010], which as is, are not suited for automated computations.

Solution

In this presentation, we give a way to define opetopes syntactically.

Syntax

Since opetopes are pasting diagrams whose cells are **many-to-one**, they can be represented as trees:



Denote by \blacklozenge the unique 0-opetope, a.k.a. the point:

٠

Denote by ♦ the unique 0-opetope, a.k.a. the point:

and by • the unique 1-opetope, a.k.a. the arrow:

· _____ ·

Denote by ♦ the unique 0-opetope, a.k.a. the point:

and by • the unique 1-opetope, a.k.a. the arrow:

We can represent **•** as a node of a tree as follows:



Denote by ♦ the unique 0-opetope, a.k.a. the point:

and by • the unique 1-opetope, a.k.a. the arrow:

We can represent **•** as a node of a tree as follows:



Let us add address information.

Idea: dimension 2

Then we can:

1. create a tree with that corolla representing •


Idea: dimension 2

Then we can:

1. create a tree with that corolla representing •



2. consider that tree as a corolla, where the input edges are the nodes

Idea: dimension 2

Then we can:

1. create a tree with that corolla representing -



- 2. consider that tree as a corolla, where the input edges are the nodes
- 3. be convinced that this is a good representation of some 2-opetope!















Idea: dimension 3





We now want a syntactic description of such trees.

Syntax

We now want a syntactic description of such trees.



In an *n*-opetope, every node is decorated by (n-1)-opetope,

Syntax

We now want a syntactic description of such trees.



In an *n*-opetope, every node is decorated by (n - 1)-opetope, but (n - 1)-opetope does not uniquely identify a node.

Syntax

We now want a syntactic description of such trees.



In an *n*-opetope, every node is decorated by (n - 1)-opetope, but (n - 1)-opetope does not uniquely identify a node. But addresses do! So we just need to describe a partial map

$$\Lambda \longrightarrow \mathbb{O}_{n-1}.$$











16

















Convention $\bullet = \{ \star \leftarrow \bullet \}$





























Reminder + convention $0 = \left| \right| = \{ \{ \bullet \} \}$




































































Reminder

$$\bullet \rightarrow * \bigg\} = \bullet$$



Reminder $= \{ * \leftarrow \bullet$

Syntax

Question

Is this an opetope?

Opt[?]: a sequent calculus for opetopes

The set of preopetopes $\ensuremath{\mathbb{P}}$ is defined by the following grammar:

$$\mathbb{P} ::= \bullet$$

$$| \qquad \left\{ \begin{array}{l} \mathbb{A} \leftarrow \mathbb{P} \\ \vdots \\ \mathbb{A} \leftarrow \mathbb{P} \\ 0 \\ 1 \\ \end{array} \right\}$$

The set of preopetopes $\ensuremath{\mathbb{P}}$ is defined by the following grammar:

$$\mathbb{P} ::= \blacklozenge$$

$$| \qquad \left\{ \begin{array}{l} \mathbb{A} \leftarrow \mathbb{P} \\ \vdots \\ \mathbb{A} \leftarrow \mathbb{P} \\ \end{array} \right.$$

$$| \qquad \left\{ \left\{ \mathbb{P} \right\} \right\}$$

System **Opt**[?] aims to characterize preopetopes that actually are opetopes.

The first rule of **Opt**[?] states that we may create points without any prior assumption:

System Opt[?]: the **shift** rule

This rule takes an opetope **p** and produces a new opetope having a unique node, decorated in **p**:



This rule takes an opetope and produces a degenerate opetope from it:

This rule glues an *n*-opetope \mathbf{q} to an (n + 1)-opetope \mathbf{p} , the latter really just being a pasting diagram of *n*-opetopes, and "glues" them together:



Theorem

Derivable preopetopes in system **Opt**[?] are in bijective correspondence with opetopes.

The proof tree of

♦ = .

is

🔶 point

The proof tree of

is

27

The proof tree of

is

$$\frac{-}{\bullet} \operatorname{point}_{\mathsf{s} \leftarrow \bullet} \operatorname{shift}_{\mathsf{s} \leftarrow \bullet}$$

27

The proof tree of



$$\frac{\overbrace{\bullet}^{\bullet} \text{ point}}{\{\ast \leftarrow \bullet \text{ shift}}$$





The proof tree of





The proof tree of



The proof tree of



The proof tree of



: 1



The proof tree of







The proof tree of



is

: 0 shift ← 1 -graft-[[]] ← 0

29

The proof tree of





The proof tree of



The proof tree of



$$\frac{\begin{array}{c} \vdots \\ 2 \\ \hline \left\{ \begin{bmatrix} 1 \leftarrow 2 \\ \end{bmatrix} \\ \hline \\ \left\{ \begin{bmatrix} 1 \leftarrow 2 \\ \\ \end{bmatrix} \\ \left\{ \begin{bmatrix} 1 \leftarrow 2 \\ \\ \end{bmatrix} \\ \\ \\ \end{bmatrix} \\ \left\{ \begin{bmatrix} 1 \\ \end{bmatrix} \\ \\ \end{bmatrix} \\ \\ \\ \\ \\ \end{array} \right\}$$


Examples



Examples



$$\frac{3}{\{[] \leftarrow 3} \text{ shift } \frac{2}{2} \text{ graft-}[[*]] \\ \frac{\{[] \leftarrow 3}{\{[[*]] \leftarrow 2\}} \text{ graft-}[[*]]$$

31

Examples



Conclusion

• In this presentation, we gave a "unnamed" way to decribe opetopes using terms and system **Opt**?.

- In this presentation, we gave a "unnamed" way to decribe opetopes using terms and system **Opt**?.
- In [Curien et al., 2019] **arXiv:1903.05848** we also present variants of this system for **opetopic sets**.

- In this presentation, we gave a "unnamed" way to decribe opetopes using terms and system **Opt**?.
- In [Curien et al., 2019] **arXiv:1903.05848** we also present variants of this system for **opetopic sets**.
- We are experimenting with those new tools to automatically check coherence laws for an appropriate definition of opetopic ∞-groupoid.

The various constructs and algorithms can be easilyTM implemented, and opetopes amount to valid proof trees. An example implementation in Python 3 is available at github.com/altaris/ opetopy, where valid proof trees are represented by certain expressions that evaluate without throwing any exception. For example:

$$\frac{p}{\left\{ [] \leftarrow p \right\}}$$
 shift

Thank you for your attention!

References i

Baez, J. C. and Dolan, J. (1998).

Higher-dimensional algebra. III. *n*-categories and the algebra of opetopes.

Advances in Mathematics. 135(2):145–206.

Cheng, E. (2003).

The category of opetopes and the category of opetopic sets.

Theory and Applications of Categories, 11:No. 16, 353–374.

Curien, P.-L., Ho Thanh, C., and Mimram, S. (2019). Syntactic approaches for opetopes. arXiv:1903.05848 [math.CT].

References ii

- Hermida, C., Makkai, M., and Power, J. (2002).
 On weak higher-dimensional categories. I. 3.
 Journal of Pure and Applied Algebra, 166(1-2):83–104.
- Ho Thanh, C. (2018a). The equivalence between opetopic sets and many-to-one polygraphs. arXiv:1806.08645 [math.CT].
 - 📔 Ho Thanh, C. (2018b).

opetopy.

https://github.com/altaris/opetopy.

- Kock, J., Joyal, A., Batanin, M., and Mascari, J.-F. (2010).
 Polynomial functors and opetopes.
 Advances in Mathematics, 224(6):2690–2737.
- Leinster, T. (2004).

Higher Operads, Higher Categories. Cambridge University Press.